

Amendments to the Specification:

Please replace the second full paragraph on page 10 with the following amended paragraph:

The arm section 43 comprises a vertical coupler 54, having a vertical coupler turret 55 attached thereto. Extending outward from said vertical coupler turret 55 is the grasping arm 52. The grasping arm 52 comprises a rectangular frame 53 having a pair of padded gripper clamping bars 49 and 50 and pneumatic cylinders (not shown) for opening and closing the padded gripper clamping bars 49 and 50. In operation, upon actuation of the pneumatic cylinders (not shown), a bank of cage bottoms or wire baskets are clamped between the padded gripper clamping bars 49 and 50. Additionally, when used in conjunction with the soil side robot 11, the vertical ~~coupler turret 45~~ coupler turret 55 serves to rotate the grasping arm 52 (B direction), providing a means for removing soiled bedding from the cage, as well as reorientation of cages prior to placement on tunnel washer conveyer 24.